

PPP: FoF

Topic FoF-NMP-2012-3

Title: SPPORT “Self-configuring Plug-n-PrOduce RoboTics”

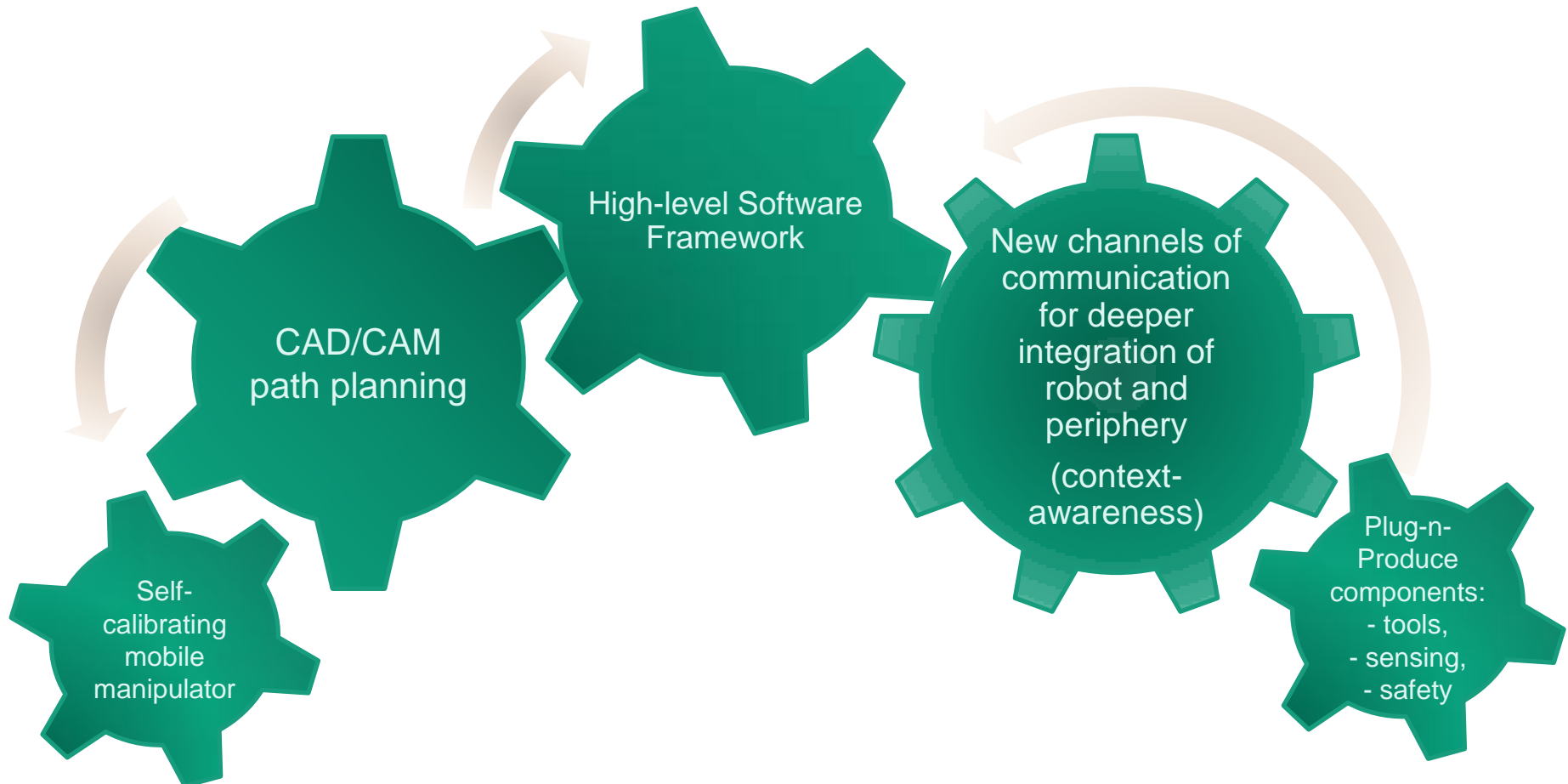
Objectives:

- Software framework for minimizing programming and configuration requirements
- Integration of Plug-and-Produce functionality in tools, sensing and safety systems

Expected results:

- Increased productivity and flexible reconfiguration of production machines
- Increased context-awareness for more versatile manufacturing

Info about project/project structure:



PPP: FoF

Title: SPPORT

Topic FoF-NMP-2012-3

Known Partners				
S.No	Partner Name	Type	Country	Role in the Project
1	Fraunhofer IFF	RTD	DE	Project coordination, software development / integration
2	Prodintec	RTD	ES	Sensor development
3	Profactor	SME	AT	CAD/CAM path planning
4		SME	ES, POR	Robotic tool manufacturer / tool development and integration in Application PnP layer
Required Partners				
S.No	Profile	Type	Country	Role in the project
	Enterprise software developer	Industry/ SME		Integration in Enterprise Software
	Manufacturer	SME		